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ESTIMATION OF SCHOOL BIOMASS AND TARGET STRENGTH
OF FJORD-FEEDING, FATTY-HERRING

by

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Abstract

The connections between reflected echo energy and dimensions of fatty herring schools were studied by a combination of multibeam sonar and a calibrated echo integration unit. A relation between area and biomass of the schools was established. A target strength relation was derived by preseining echo integration and sonar measurements of schools. Method deficiencies and improvements for school biomass estimation using sonar and preseining target strength measurements are discussed.

Introduction

Correct estimation of school biomass during purse seining is mostly dependent on the skipper's experience and intuition in relating echo recordings to biomass. During conventional echo integration surveys, schools avoiding the vessel will lead to significant underestimation of fish abundance (Olsen et. al. 1983). Use of sector scanning sonars may reduce this sampling error due to their greater volume coverage compared to single beam transducers (Ehrenberg 1980). Biomass measuring of schools with sector scanning sonars may increase the precision of abundance estimation of pelagic stocks, and be a helpful tool in tactical planning of purse seine operations.

Sector scanning sonars can be used to measure both horizontal and vertical school dimensions (Gunderson et. al. 1982, Wilkins 1986), and a computerized sonar can provide a scaled echo quantity of recorded schools (Bodholt 1982). However, relations to convert dimensions and echo quantity to absolute school biomass has been difficult to establish (Hewitt, Smith & Brown 1976). To investigate possible connections between school dimensions and reflected echo energy, fatty-herring schools were measured by a multibeam sonar and a calibrated echo integration unit. Fish densities as measured by echo integration or estimated from purse seine capture of sonar measured schools were compared. By use of the density estimates from purse seining, a target strength relation of the fatty-herring was derived.

Materials and Methods

The investigations were made from M/V "Fjordfangst" in Romsdalsfjord, North Western Norway, in September 1987. The 42 feet vessel was rigged with a 320 m long and 45 m deep herring purse-seine, and equipped with an echo integration system (70 kHz Simrad EY-M echo sounder connected to a Simrad QM echo integrator) and a sonar (150 kHz Furuno CH-12). The acoustic system was calibrated according to standard methods

(Foote et. al. 1987), and the instrument settings and calibration results are given in Appendix.

Temperature gradients in the Fjord (Fig. 1) caused deflection of the emitted sonar beams (Smith 1977), and schools were detected < 300 m from the vessel. A total of 36 schools were recorded. The sonar projection of the schools was measured perpendicular to the beams (cw) and along the beams (lw) by a ruler (Fig. 2). The horizontal distance vessel-school (R) was measured by the sonar marker. After dimensioning, the vessel was manoevered over the centre of the school at a speed of approximately 4 knots to record the reflected echo energy (M) and vertical extension (h). Eight of the schools were measured 4 - 5 times at intervals of 3 - 5 minutes. The dimensions and densities (method A) were computed by:

$$(3) \text{ Crosswise extension} : CW = cw s - 2 R \tan B \quad (\text{m})$$

$$(4) \text{ Lengthwise extension} : LW = lw s - (c t_s)/2 \quad (\text{m})$$

$$(5) \text{ Vertical extension} : H = h - (c t_e)/2 \quad (\text{m})$$

$$(6) \text{ School area} : A = ((CW LW)/4) \pi \quad (\text{m}^2)$$

$$(7) \text{ School volume} : V = (4/3 A H/2) \quad (\text{m}^3)$$

$$(8) \text{ Fish density: } D = (C_i M k_{nm}) / (4 \pi \sigma_{bs} k_{nm}^2 LW H) \quad (\text{n/m}^3)$$

c : speed of sound (~ 1500 m/s)

2 B: beamwidth of the sonar (6° at the transmitter)

t_s : sonar pulselength (2.8 ms at sonar range of 200 m)

t_e : echo sounder pulselength (0.6 ms)

s : sonar scaling factor (sonar distance/screen distance)

σ_{bs} : back scattering cross section of herring calculated by target strength (38 kHz) = 20 log L - 73.5 (Foote 1987)

k_{nm} : number of metres in one nautical mile

C_i : system calibration coefficient

The target strength of the herring was adjusted for the frequency of the echo sounder by addition of 4.5 (log f_a - log f_b) where f_a = 70 kHz and f_b = 38 kHz (MacCartney & Stubbs 1971).

The school biomass was estimated by multiplying the school area by the number of fish per unit area and by the average fish weight (W) computed by:

$$(9) \quad W = 1.508 \cdot 10^{-3} L^{3.519} \quad (\text{Simmonds et. al. 1986})$$

Two of the measured schools were captured by purse seine, and the fish densities alternatively estimated (method B) by dividing the number of captured fish by the school volume. The number of fish was calculated from a catch volume estimated by our skipper. These densities enabled an independent calculation of the target strength of the herring. This was done by rearranging equation 8 to calculate the back scattering cross section, and hence the target strength = $10 \log \sigma_{bs}$ (MacCartney & Stubbs 1971).

RESULTS

The schools were recorded in daylight at depths from 7 to 58 meters. The herring in sub-samples from four catches averaged 28.1 cm long (Fig. 3), immature or slightly maturing, with considerable abdominal fat, and stomachs full of *Calanus* sp. On eleven occasions the schools approached were strongly avoiding the vessel and not recorded on the echo sounder. At dawn the schools dispersed (Pitcher 1983), too diffuse to enable exact dimensional measurement.

The lengthwise and crosswise extension of the schools were on average about equal, but greater than the average vertical extension (Table 1). No correlation between the horizontal dimensions ($r=0.07$, $p>0.05$) indicates an elliptical or rectangular school shape. However, on one occasion a relatively large, parabolic shaped school was recorded, as swimming perpendicular to the convex side (Fig. 4). The vertical school extension (H) seems to increase asymptotically with the area (A) (Fig. 5 A), expressed by:

$$H = 1.61 A^{0.37} \quad (r = 0.45, p < 0.05)$$

On average, the school areas amounted about 800 m², the school volumes about 13 000 m³, but the school dimensions varied considerably (Table 1). The average fish density of the schools was 4.3 herring/m³, but with high variance. There was considerable variation in repeated measurements of the eight schools (Table 1), but average coefficient of variation (ACOVAR) was greatest for the crosswise extension ($p < 0.05$). The unstable dimensions induced great variation in estimated area, volume and densities of these schools with average coefficients of variation ranging from 0.49 to 0.82.

Both the reflected echo energy (M) and the calculated biomass (B) of the schools increased with school the area (A) (Fig. 5 B,C). The relationships are expressed by:

$$M = 0.0089 (A) + 2.3 \quad (r = 0.56, p < 0.05)$$

$$B = 256 A^{0.46} \quad (r = 0.68, p < 0.05)$$

Two schools, which had been dimensioned and measured for reflected echo energy were captured (Table 2). The difference in fish density as measured by the echo energy method (A) or estimated by the catch volume method (B) was < 1 herring/m³. Calculated target strengths deviate 0.4 dB, but the largest herring gave the lowest target strength. Deduced 20 log L target strength relations indicate a difference of 1 dB in the two estimates. By linear averaging of these two estimates and referring to herring of 28.0 cm, the following target strength relation was derived:

$$TS (70 \text{ kHz}) = 20 \log L - 73.6$$

DISCUSSION

The schools were considered ellipsoid for the calculation of their area and volume. An average proportion between the crosswise and lengthwise extensions of 1.7 : 1.8, indicates a circular school shape when the sonar distortion is taken into account (Misund 1987). However, no correlation between the

horizontal dimensions might also be explained with elliptic schools having random orientation of their axis relative to the vessel. This is different from other measurements of herring schools, where the elliptic shape of schools guided by the vessel was more apparent (Misund 1987). An elliptic shape of clupeidae and scombroidae schools are repeatedly reported (Bolster 1958, Cushing 1960, Anon 1974, Squire 1978), even if schools are claimed to be amorphous (Radakov 1973). The observed parabolic shape may be an adaptation to combined feeding/migration behavior as reported for hunting bluefin tuna (Partridge, Johansson & Kalish 1983). Our method of measuring the school area would give erroneous estimates of parabolic shaped schools.

The average proportion between the horizontal and vertical extension of the schools of about 1.75 : 1 is in accordance with similar proportions for herring, mullet, pilchard and saithe schools kept in aquaria or observed in nature (Breder 1959, Cullen et. al. 1965, Pitcher & Partridge 1979). However, the vertical extension seems to increase asymptotically with the area of the schools, indicating influence of biotic and abiotic factors on school organization.

The average horizontal extension of the schools was about 800 m². This is less than the average school area of prespawning herring of the same stock and of summer-feeding North Sea herring schools, both sonar measured during purse seining (Misund 1987). This comparison is rather uncertain since small schools mostly are ignored during fishing. However, changes in biological conditions and sea environment may induce seasonal variations in school size (Devold 1969, Mohr 1971, Smith 1981).

Variation in dimensions from repeated measurements of the single school may be due to tightening or loosening of the school structure through changing swimming speed (Partridge et. al 1980), or because parts of the school are not insonified (Misund 1987). The relative variation in the crosswise

extension was twice that of the lengthwise and vertical extension of the schools. As pointed out by Halvorsen (1985), the applied average beamwidth correction is rather uncertain. This might have induced the relatively large variation in the crosswise extension of the single school.

The fish density in the recorded schools is one order of magnitude less than can be calculated from a school volume-to-average body length relation observed in aquaria (Pitcher & Partridge 1979). Comparisons between densities observed in nature and in a laboratory are probably doubtful since "aquaria" schools are organized in an environment with limited extension. The average fish density of about 4 herring/m³ is comparable to 3.1 herring/m³ as predicted by a density relation (Serebrov 1976, 1984). Buerkle (1987) obtained fish densities from combined photographic and acoustic measurements of a large herring aggregation more than one order of magnitude lower, but his results may be biased by fish avoidance, and limitations of his camera system. Other studies quote 1 herring/m³ (Radakov 1973, Cushing 1977).

However, the measured densities may be biased by assuming a too low target strength, which on the other hand may be partly corrected by a too high frequency compensation (Ona 1982). Maybe the frequency compensation should have been negative since herring exhibit a falling frequency response from 27 to 54 kHz (Simmonds 1986). Errors in the measurement of the system calibration constant, and absorption of the emitted sound beam in dense concentrations (Røttingen 1976) may have influenced the results. However, the most serious source of bias is probably systematic avoidance by the herring schools (Olsen et. al. 1983, Misund 1987). Sideway avoidance may result in a systematic lower lengthwise extension recorded by the echo sounder than measured at the sonar projection. If the herring avoids the approaching vessel by downward swimming, a large reduction in its target strength may occur (Olsen 1987).

The great variation in the measured fish density may reflect natural density variations caused by the internal school dynamic (Van Olst & Hunter 1971), or by lacunas between subunits in the school (Pitcher & Partridge 1979, Serebrov 1984). Varying measurement errors of the lengthwise school extension are also a plausible cause. Probably the method would have been more accurate by using the length of the school recorded by the echo sounder instead of the lengthwise extension of the sonar projections. In addition, inaccurate readings of the reflected echo energy and the vertical extension of the school may have influenced the results.

The school area increased both with reflected echo energy and calculated biomass of the schools. This is in accordance with acoustic theory and the knowledge of schooling behaviour. Reflected echo energy from a recorded school section is proportional to the average target strength of the individuals plus 10 times the number of individuals in the recorded section (Mitson 1983). The volume of a school is proportional to the number of individuals multiplied by the cube of the average body length (Pitcher & Partridge 1979). Consequently, the area of a horizontal section through the school is proportional to the number of individuals in the section multiplied by the square of the average body length. The relations are comparable to a correlation between purse seine catches and echo integrator values of pacific herring shoals (Mulligan, Kieser & Gjernes 1987).

Relatively large variations in the relations between school area, reflected echo energy and school biomass were apparent. In addition to natural density variations and the deficiencies in the method already commented, this may be due to uncertainty in measuring the reflected echo energy from a representative section of the school. This problem can be exemplified by assuming a circular school shape which results in a probability to record the diameter of the school proportional to $\pi/4$ (Olsen 1969). Even if the direction of the vessel was adjusted to ensure passage over the centre of the

school, many schools showed sideways avoidance. About 25 % of the sonar located schools avoided the approaching vessel strongly, and were not recorded on the echo sounder.

Another serious source of variation is that some of the recorded schools might have been formed by species with a target strength different of herring. In the actual area saithe (*Pollachius virens*) were present, and one purse seine trial gave a 5000 kg catch of about 35 cm long saithe. It is difficult to separate sonar and echo sounder recordings by species, and all recorded school except the saithe school caught, were therefore considered to be herring.

The difference in fish densities estimated by reflected echo energies or by catch volumes in two dimension measured, purse seine capture schools was less than 1 herring/m³. Ignoring the frequency dependence, the derived target strength equation is very close to a relation obtained by Hagstøm & Røttingen (1983) in a similar experiment. Since our target strength relation is based on uncontrollable catch volume estimates, this should be interpreted rather as coincidence than an argument for confidence in the relation. However, even if an experienced skipper to some extent gives reliable catch estimates (Mulligan, Kieser & Gjernes 1987), accurate measurement makes the method confident.

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Table 1. Dimensions, area, volume and fish density by 57 measurements (totaly) of 36 recorded herring schools, and average coefficient of variation (ACOVAR) in repeated (4-5) measurements of 8 schools.

	Dimensions			Area (m ²)	Volume (m ³)	Fish density	
	CW (m)	LW (m)	H (m)			(n/m ²)	(n/m ³)
Average	31.0	33.5	18.9	836.6	12852	82.5	4.3
St. Dev.	19.4	19.4	8.7	881.0	18178	104.5	4.0
ACOVAR	0.51	0.20	0.29	0.49	0.63	0.82	0.72

Table 2. School dimensions, fish density and target strength of herring in two schools captured by purse seine (A: echo energy method, B: catch volume method).

	Catch volume (hl)	School area (m ²)	School volume (m ³)	Fish length (cm)	Fish weight (kg)	Fish density (n/m ³)		Fish TS (dB)
						A	B	
School 1	20	142	1989.0	27.0	0.164	6.17	5.7	-44.5
School 2	100	781.1	6251.8	28.9	0.209	6.12	7.1	-44.9

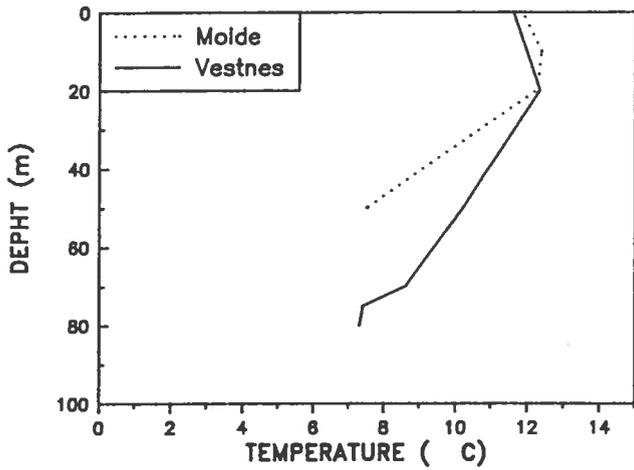


Fig. 1. Temperature profiles from the school recording area.

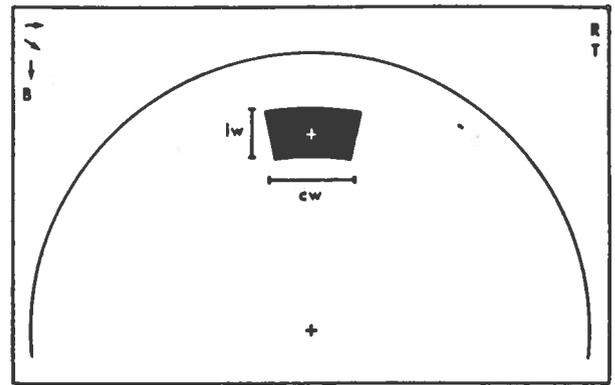


Fig. 2. Measurement of lengthwise (lw) and crosswise (cw) school extension, and horizontal distance vessel-school at the sonar screen.

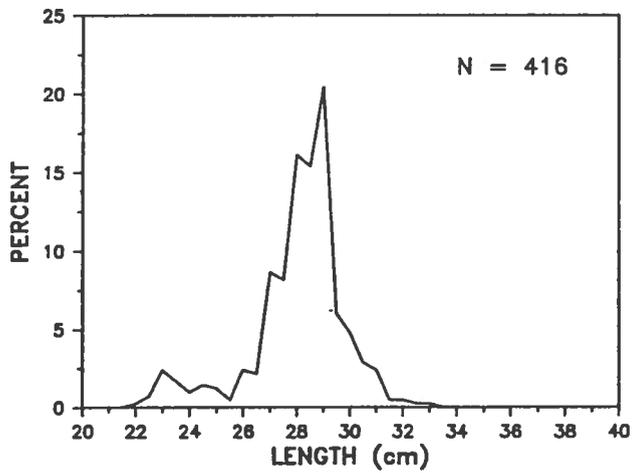


Fig. 3. Length distribution from four herring catches.

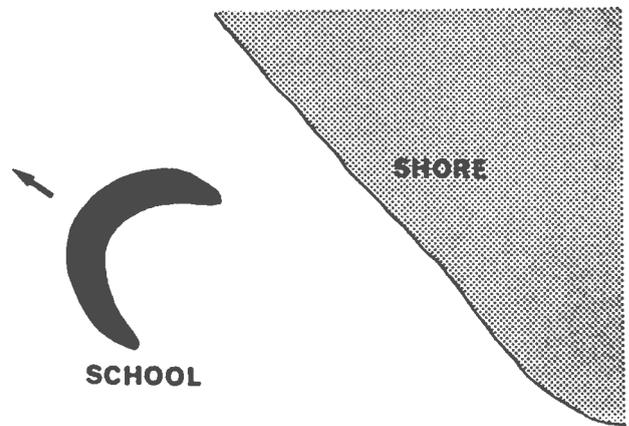


Fig. 4. Recorded parabolic shaped school with swimming direction as indicated by the arrow.

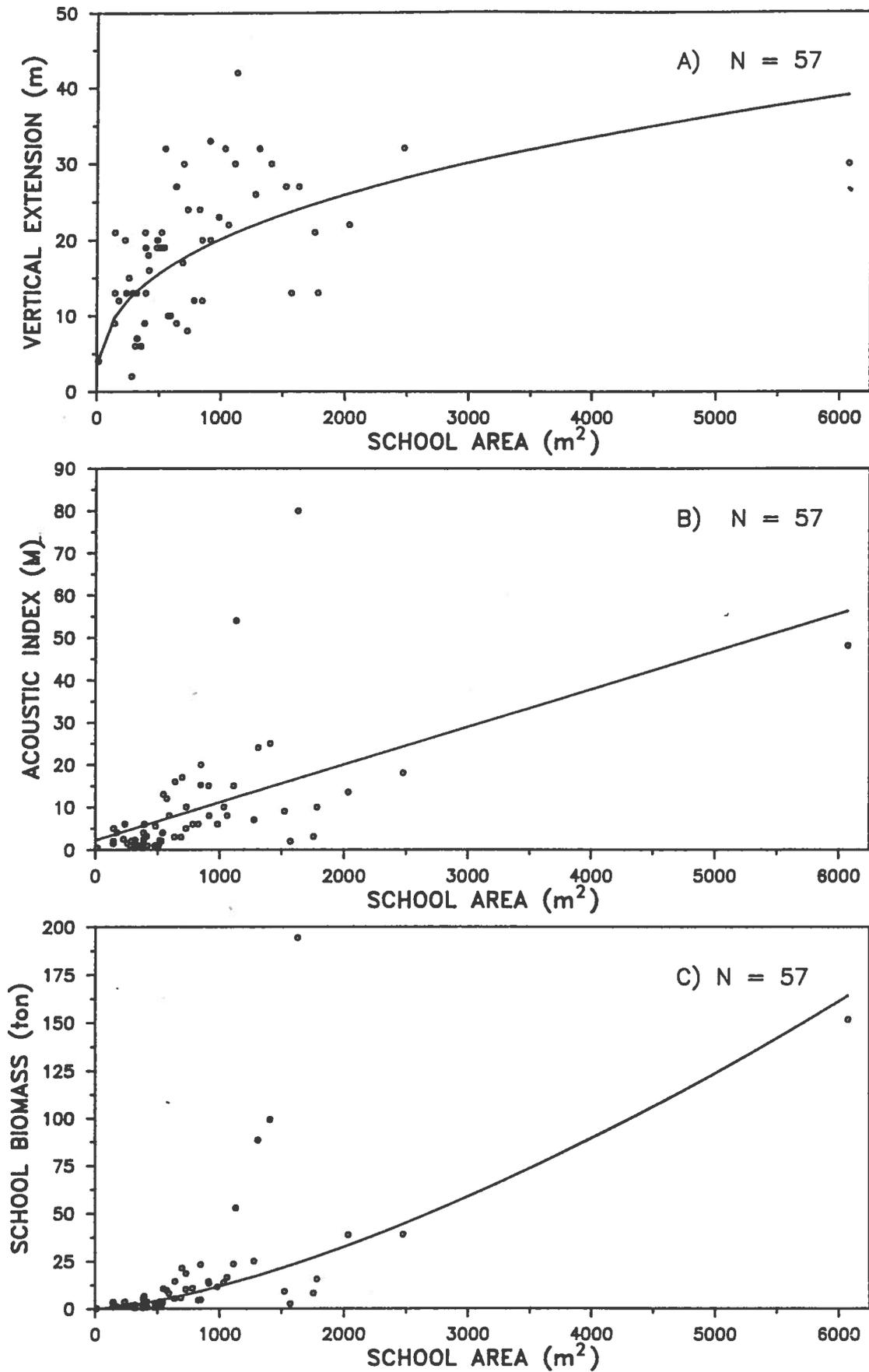


Fig. 5. Estimated school area related to vertical extension (A), acoustic index (integrator output, B), and calculated school biomass (C).

APPENDIX

Instrument settings and calibration results

Simrad EY-M echo sounder

Gain (step)	5
Scale (meter)	0 - 60
Source level (SL) + Voltage response (VR) (dB)	108

Simrad OM echo integrator

Threshold (dB)	0
Gain (dB)	-20
Channel 1 (meter)	0 - 60
Channel 2 (meter)	60 - 120

System calibration constant (C_i)	328.6
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